

Deformations of exact and homogeneous Poisson pencils of hydrodynamic type

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Based on joint works with A. Arsie and with G. Falqui

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Plan of the talk

- An example: the scalar case.
- Deformations of semisimple Poisson pencils of hydrodynamic type and their central invariants. (Dubrovin, Liu and Zhang).
- Deformations of exact, semisimple Poisson pencils of hydrodynamic type (joint work with Gregorio Falqui: to appear in Physica D).
- The case of non constant central invariants (joint work with A. Arsie: **arXiv:1107.2327**).

The scalar case

$$\omega_\lambda = \omega_2 - \lambda\omega_1 = u\delta'(x-y) + \frac{1}{2}u_x\delta(x-y) - \lambda\delta'(x-y)$$

It is exact:

$$\text{Lie}_e\omega_1 = 0$$

$$\text{Lie}_e\omega_2 = \omega_1.$$

with $e = \frac{\partial}{\partial u}$.

It is homogeneous:

$$\text{Lie}_E\omega_1 = (d-2)\omega_1$$

$$\text{Lie}_E\omega_2 = (d-1)\omega_2.$$

with $d = 0$ and $E = u\frac{\partial}{\partial u}$.

$$\Pi_{\lambda}^{ij} = \omega_{\lambda} + \sum_{k=1}^{\infty} \epsilon^{2k} P_2^{(k)}.$$

Second order deformation (PL, 2002):

$$P_2^{(2)} = \left\{ \partial_x^2 \left(c_2 \delta^{(1)}(x-y) \right) + c_2 \delta^{(3)}(x-y) + (\partial_x c_2) \delta^{(2)}(x-y) \right\}$$

where $c_2 = c_2(u)$ is an arbitrary function.

Fourth order:

$$P_2^{(4)} = \left\{ \partial_x^4 \left(c_4 \delta^{(1)}(x-y) \right) + c_4 \delta^{(5)}(x-y) + (\partial_x c_4) \delta^{(4)}(x-y) \right\}$$

where $c_4 = \frac{\partial}{\partial u} (c_2)^2$.

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Sixth order (A. Arsie, PL, 2011):

$$\begin{aligned}
 P_2^{(6)} = & \\
 = & \left\{ \partial_x^6 \left(c_6 \delta^{(1)}(x-y) \right) + c_6 \delta^{(7)}(x-y) + (\partial_x c_6) \delta^{(6)}(x-y) \right\} \\
 & + \left\{ h \delta^{(3)}(x-y) + (\partial_x h) \delta^{(2)}(x-y) + \partial_x^2 \left(h \delta^{(1)}(x-y) \right) \right\} \\
 & + \left\{ \partial_x \left((\partial_x^3 g) \delta^{(3)}(x-y) \right) + (\partial_x^2 g) \delta^{(5)}(x-y) + (\partial_x^3 g) \delta^{(4)}(x-y) \right. \\
 & \left. + \partial_x^3 \left((\partial_x^2 g) \delta^{(2)}(x-y) \right) \right\},
 \end{aligned}$$

where

$$c_6 = -\frac{1}{2} \frac{\partial}{\partial u} \left(c_2^2 \frac{\partial c_2}{\partial u} \right),$$

$$g = \frac{1}{2} \int \left\{ \frac{3}{2} c_2^2 \frac{\partial^3 c_2}{\partial u^3} + \left(\frac{\partial c_2}{\partial u} \right)^3 + \frac{19}{3} c_2 \frac{\partial^2 c_2}{\partial u^2} \frac{\partial c_2}{\partial u} \right\} du$$

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$$\begin{aligned}
h = & \left[\frac{97}{60} c_2 \left(\frac{\partial^2 c_2}{\partial u^2} \right)^2 + \frac{8}{3} \left(\frac{\partial c_2}{\partial u} \right)^2 \frac{\partial^2 c_2}{\partial u^2} + \frac{21}{40} c_2^2 \frac{\partial^4 c_2}{\partial u^4} \right. \\
& + \frac{49}{15} c_2 \left(\frac{\partial^3 c_2}{\partial u^3} \right) \frac{\partial c_2}{\partial u} \left. \right] u_{xx}^2 + \left[\frac{254}{3} \left(\frac{\partial c_2}{\partial u} \right)^2 \frac{\partial^4 c_2}{\partial u^4} + \frac{17}{5} c_2^2 \frac{\partial^6 c_2}{\partial u^6} \right. \\
& + \frac{176}{3} c_2 \left(\frac{\partial^3 c_2}{\partial u^3} \right)^2 + \frac{4018}{45} c_2 \left(\frac{\partial^4 c_2}{\partial u^4} \right) \frac{\partial^2 c_2}{\partial u^2} + \frac{1684}{45} c_2 \frac{\partial^5 c_2}{\partial u^5} \frac{\partial c_2}{\partial u} \\
& + \frac{14512}{45} \left(\frac{\partial c_2}{\partial u} \right) \left(\frac{\partial^2 c_2}{\partial u^2} \right) \frac{\partial^3 c_2}{\partial u^3} \left. \right] u_x^4 + \left[\frac{3}{10} c_2^2 \frac{\partial^4 c_2}{\partial u^4} + \right. \\
& \frac{2}{3} \left(\frac{\partial c_2}{\partial u} \right)^2 \frac{\partial^2 c_2}{\partial u^2} + \frac{1}{15} c_2 \left(\frac{\partial^2 c_2}{\partial u^2} \right)^2 + \frac{28}{15} c_2 \left(\frac{\partial^3 c_2}{\partial u^3} \right) \frac{\partial c_2}{\partial u} \left. \right] u_{xxx} u_x \\
& + \left[\frac{139}{10} \left(\frac{\partial c_2}{\partial u} \right) \left(\frac{\partial^2 c_2}{\partial u^2} \right)^2 + \frac{178}{15} \left(\frac{\partial c_2}{\partial u} \right)^2 \frac{\partial^3 c_2}{\partial u^3} + \frac{21}{20} c_2^2 \frac{\partial^5 c_2}{\partial u^5} \right. \\
& + \frac{259}{30} c_2 \left(\frac{\partial^4 c_2}{\partial u^4} \right) \frac{\partial c_2}{\partial u} + 13 c_2 \left(\frac{\partial^2 c_2}{\partial u^2} \right) \frac{\partial^3 c_2}{\partial u^3} \left. \right] u_{xx} u_x^2.
\end{aligned}$$

Remarks

1. In the case $c_2 = \text{constant}$ (KdV) the full pencil $\Pi_\lambda = P_2 - \lambda P_1$ is exact:

$$\text{Lie}_e P_2 = P_1, \quad \text{Lie}_e P_1 = 0$$

where $e = \frac{\partial}{\partial u}$.

2. In the case $c_2 = u^D$:

$$\text{Lie}_E P_2^{(2k)} = (kD - k - 1)P_2^{(2k)},$$

where $E = u \frac{\partial}{\partial u}$.

Local multivectors and Schouten bracket

Λ_{loc}^j = space of local multivectors

$$\alpha^{i_1, \dots, i_j} = \sum_{l_2, \dots, l_j} A_{l_2, \dots, l_j}^{i_1, \dots, i_j}(u(x_1), u_{x_1}, \dots) \delta^{(l_2)}(x_1 - x_2) \dots \delta^{(l_j)}(x_1 - x_j)$$

Associated superfunctional

$$\hat{\alpha} = \int \sum_{l_2, \dots, l_j} A_{l_2, \dots, l_j}^{i_1, \dots, i_j}(u(x_1), u_{x_1}, \dots) \theta_{i_1} \theta_{i_2}^{(l_2)} \dots \theta_{i_k}^{(l_j)} dx$$

Schouten bracket

$$[\alpha, \beta] := \{\hat{\alpha}, \hat{\beta}\} = \int \left(\frac{\delta \hat{\alpha}}{\delta \theta^i} \frac{\delta \hat{\beta}}{\delta u^i} + (-1)^{|\alpha|} \frac{\delta \hat{\alpha}}{\delta u^i} \frac{\delta \hat{\beta}}{\delta \theta^i} \right) dx$$

where $|\alpha|$ is the parity of α .

A local bivector Π is called *Poisson bivector* iff $[\Pi, \Pi] = 0$.

Poisson bivectors of hydrodynamic type

PBHT (Dubrovin-Novikov):

$$\omega^{ij} = g^{ij} \delta'(x - y) - g^{il} \Gamma_{lk}^j u_x^k \delta(x - y)$$

- g is a flat metric.
- Γ_{lk}^j are the Christoffel symbols of the associated Levi-Civita connection.

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Deformations of PBHT

A local bivector

$$P = \omega + \epsilon P^{(1)} + \epsilon^2 P^{(2)} + \dots + \epsilon^l P^{(l)} + \dots,$$

is called a deformation of ω if

$$[P, P] = 0, \quad \deg P^{(l)} = l + 2$$

Degree:

- $\deg f(u) = 0$
- ∂_x increases the degrees by one
- $\deg \delta(x - y) = 1$

This implies:

$$(P^{(l)})^{ij} = \sum_{s=0}^{l+1} A_k^{ij}(u, u_x, \dots) \delta^{(l+1-k)}(x - y), \quad \deg A_k^{ij} = k$$

Triviality of deformations and Poisson-Lichnerowicz cohomology

Theorem

All deformations are trivial: there exists a Miura transformation

$$u^i \rightarrow \tilde{u}^i = F_0^i(u) + \sum_k \epsilon^k F_k^i(u, u_x, \dots), \quad \deg F_k^i = k$$

reducing $P = \omega + \epsilon P^{(1)} + \dots$ to its dispersionless limit ω .

The proof is by induction using

Theorem

$H^j(\omega) = 0$ for all positive integers (Getzler in the general case, Degiovanni-Magri-Sciacca, Dubrovin-Zhang in the case $j = 1, 2$).

where

$$H^j(\omega) := \frac{\ker\{d_\omega : \Lambda_{\text{loc}}^j \rightarrow \Lambda_{\text{loc}}^{j+1}\}}{\text{im}\{d_\omega : \Lambda_{\text{loc}}^{j-1} \rightarrow \Lambda_{\text{loc}}^j\}}, \quad d_\omega := [\omega, \cdot]$$

Poisson pencils of hydrodynamic type

$$\omega_{\lambda}^{ij} = \omega_2^{ij} - \lambda \omega_1^{ij} = g_2^{ij}(u) \delta'(x-y) + \Gamma_{(2)k}^{ij} u_x^k \delta(x-y) + \\ - \lambda \left(g_1^{ij}(u) \delta'(x-y) + \Gamma_{(1)k}^{ij} u_x^k \delta(x-y) \right)$$

- $g_{\lambda}^{ij} = g_2^{ij} - \lambda g_1^{ij}$ is flat $\forall \lambda$.
- $\Gamma_{(\lambda)k}^{ij} = \Gamma_{(2)k}^{ij} - \lambda \Gamma_{(1)k}^{ij}$
- $d_{\omega_1} d_{\omega_2} + d_{\omega_2} d_{\omega_1} = 0$, $(d_{\omega_1} = [\omega_1, \cdot], d_{\omega_2} = [\omega_2, \cdot])$

Semisimplicity assumption: the roots (r^1, \dots, r^n) of the equation $\det g_{\lambda} = 0$ are functional independent. They are called *canonical coordinates*. In canonical coordinates

$$g_1^{ij} = f^i(r^1, \dots, r^n) \delta_j^i, \quad g_2^{ij} = r^i f^i(r^1, \dots, r^n) \delta_j^i.$$

Poisson pencils of hydrodynamic type

$$\omega_{\lambda}^{ij} = \omega_2^{ij} - \lambda \omega_1^{ij} = g_2^{ij}(u) \delta'(x-y) + \Gamma_{(2)k}^{ij} u_x^k \delta(x-y) + \\ - \lambda \left(g_1^{ij}(u) \delta'(x-y) + \Gamma_{(1)k}^{ij} u_x^k \delta(x-y) \right)$$

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Central invariants

Deformations of semisimple Poisson pencils of hydrodynamic type

$$\Pi_{\lambda}^{ij} = \omega_{\lambda} + \epsilon \left[P_{\lambda}^{ij} \delta''(x-y) + \cdots \right] + \epsilon^2 \left[Q_{\lambda}^{ij} \delta'''(x-y) + \cdots \right] + \mathcal{O}(\epsilon^3)$$

where $P_{\lambda}^{ij} = P_2^{ij} - \lambda P_1^{ij}$ and $Q_{\lambda}^{ij} = Q_2^{ij} - \lambda Q_1^{ij}$.

Central invariants:

$$c_i(r^i) = -\frac{1}{3f^i} \operatorname{Res}_{\lambda=r^i} \operatorname{Tr} g_{\lambda}^{-1} A_{\lambda}$$

where the tensor A_{λ}^{ij} is defined by

$$A_{\lambda}^{ij} = Q_{\lambda}^{ij} + (g_{\lambda}^{-1})_{lk} P_{\lambda}^{li} P_{\lambda}^{kj}.$$

Theorem

Two deformations of the same Poisson pencil of hydrodynamic type are Miura equivalent iff they have the same central invariants (Dubrovin-Liu-Zhang).

Central invariants

Deformations of semisimple Poisson pencils of hydrodynamic type

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Example 1: AKNS

$$\omega_2 + \epsilon P_2^{(1)} - \lambda \omega_1 = \begin{pmatrix} (2u\partial_x + u_x)\delta & v\delta' \\ \partial_x(v\delta) & -2\delta' \end{pmatrix} + \epsilon \begin{pmatrix} 0 & -\delta'' \\ \delta'' & 0 \end{pmatrix} - \lambda \begin{pmatrix} 0 & \delta' \\ \delta' & 0 \end{pmatrix}$$

In this case we have

$$g_\lambda = \begin{pmatrix} 2u & v - \lambda \\ v - \lambda & -2 \end{pmatrix}, \quad A_\lambda = \frac{g_\lambda}{\det g_\lambda}$$

Canonical coordinates: $r^1 = v + \sqrt{-4u}$, $r^2 = v - \sqrt{-4u}$

Diagonal components of g_1 : $f^1 = \frac{8}{r_2 - r_1}$, $f^2 = \frac{8}{r_1 - r_2}$

$$c_1 = -\frac{1}{3f^1} \operatorname{Res}_{\lambda=r^1} \operatorname{Tr} g_\lambda^{-1} A_\lambda = -\frac{1}{3f^1} \operatorname{Res}_{\lambda=r^1} \frac{2}{\det g_\lambda} = -\frac{1}{12}$$

$$c_2 = -\frac{1}{3f^2} \operatorname{Res}_{\lambda=r^2} \operatorname{Tr} g_\lambda^{-1} A_\lambda = -\frac{1}{3f^2} \operatorname{Res}_{\lambda=r^2} \frac{2}{\det g_\lambda} = -\frac{1}{12}$$

Two component CH (Chen-Liu-Zhang, Falqui)

$$P_\lambda = \begin{pmatrix} (2u\partial_x + u_x)\delta & v\delta' \\ \partial_x(v\delta) & -2\delta' \end{pmatrix} - \lambda \begin{pmatrix} 0 & \delta' - \epsilon\delta'' \\ \delta' + \epsilon\delta'' & 0 \end{pmatrix}$$

$$g_\lambda = \begin{pmatrix} 2u & v - \lambda \\ v - \lambda & -2 \end{pmatrix}, \quad A_\lambda = \frac{\lambda^2 g_\lambda}{\det g_\lambda}$$

$$\begin{aligned} c_1 &= -\frac{1}{3f^1} \operatorname{Res}_{\lambda=r^1} \operatorname{Tr} g_\lambda^{-1} A_\lambda = -\frac{1}{3f^1} \operatorname{Res}_{\lambda=r^1} \frac{2\lambda^2}{\det g_\lambda} = -\frac{(r^1)^2}{12} \\ c_2 &= -\frac{1}{3f^2} \operatorname{Res}_{\lambda=r^2} \operatorname{Tr} g_\lambda^{-1} A_\lambda = -\frac{1}{3f^2} \operatorname{Res}_{\lambda=r^2} \frac{2\lambda^2}{\det g_\lambda} = -\frac{(r^2)^2}{12}. \end{aligned}$$

Exact Poisson pencil

The Poisson pencil

$$\Pi_\lambda = P_2 - \lambda P_1$$

is exact iff there exists a vector field Z , called *Liouville* vector field, such that

$$\bullet \operatorname{Lie}_Z P_2 = P_1$$

$$\bullet \operatorname{Lie}_Z P_1 = 0$$

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Exact Poisson pencil of hydrodynamic type

Theorem

A semisimple Poisson pencil of hydrodynamic type is exact if and only if the condition

$$\sum_{k=1}^n \frac{\partial f^i}{\partial r^k} = 0.$$

is satisfied.

Moreover, in canonical coordinates all the components of the vector field Z are equal to 1 (i.e. $Z = e$).

Consequences of exactness:

$$\bullet \operatorname{Lie}_e d_{\omega_1} - d_{\omega_1} \operatorname{Lie}_e = 0$$

$$\bullet \operatorname{Lie}_e d_{\omega_2} - d_{\omega_2} \operatorname{Lie}_e = 0$$

$$\bullet \operatorname{Lie}_e d_{\omega_3} - d_{\omega_3} \operatorname{Lie}_e = 0$$

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- $\text{Lie}_e d_{\omega_2} - d_{\omega_2} \text{Lie}_e = d_{\omega_1}$
- $\text{Lie}_e d_{\omega_1} d_{\omega_2} - d_{\omega_1} d_{\omega_2} \text{Lie}_e = 0$

Costancy of the central invariants = exactness

Theorem

Let

$$\Pi_\lambda = P_2 - \lambda P_1 = \omega_2 + \sum_{k=1}^{\infty} \epsilon^{2k} P_2^{(2k)} - \lambda \left(\omega_1 + \sum_{k=1}^{\infty} \epsilon^{2k} P_1^{(2k)} \right).$$

be a Poisson pencil whose dispersionless limit $\omega_2 - \lambda\omega_1$ is semisimple and exact. Then its central invariants are constant if and only if it is exact.

Costancy of the central invariants implies exactness

Step 1: reduce Π_λ to the “standard form”

$$\Pi_\lambda = \omega_\lambda + \epsilon^2 \text{Lie}_{X_{(c_1, \dots, c_n)}} \omega_1 + \sum_{k=2}^{\infty} \epsilon^{2k} P_2^{(2k)}$$

where $X_{(c_1, \dots, c_n)} = d_{\omega_2} K + d_{\omega_1} H$ with

$$K = \sum_{i=1}^n \int c^i(r^i) r_x^i \log r_x^i dx, \quad H = - \sum_{i=1}^n \int r^i c^i(r^i) r_x^i \log r_x^i dx$$

Step 2: show that $\text{Lie}_e P_2^{(2)} = 0$. Indeed:

$$\text{Lie}_e \text{Lie}_{X_{(c_1, \dots, c_n)}} \omega_1 = \text{Lie}_{[e, X_{(c_1, \dots, c_n)}}] \omega_1 = 0$$

since $[e, X_{(c_1, \dots, c_n)}] = X_{(\frac{\partial c_1}{\partial r^1}, \dots, \frac{\partial c_n}{\partial r^n})}$.

Step 3: to construct a Miura transformation

$$\Pi_\lambda \rightarrow \tilde{\Pi}_\lambda = \omega_\lambda + \sum_{k=1}^{\infty} \epsilon^{2k} \tilde{P}_2^{(2k)}, \quad \text{Lie}_e \tilde{P}_2^{(2k)} = 0, \quad k = 1, 2, \dots$$

Costancy of the central invariants implies exactness

Step 1: reduce Π_λ to the “standard form”

$$\Pi_\lambda = \omega_\lambda + \epsilon^2 \text{Lie}_{X_{(c_1, \dots, c_n)}} \omega_1 + \sum_{k=2}^{\infty} \epsilon^{2k} P_2^{(2k)}$$

where $X_{(c_1, \dots, c_n)} = d_{\omega_2} K + d_{\omega_1} H$ with

$$K = \sum_{i=1}^n \int c^i(r^i) r_x^i \log r_x^i dx, \quad H = - \sum_{i=1}^n \int r^i c^i(r^i) r_x^i \log r_x^i dx$$

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Step 3: to construct a Miura transformation

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Exactness implies the costancy of the central invariants

Step 1: reduce Π_λ to the form

$$\Pi_\lambda = \omega_\lambda + \epsilon^2 \left(\text{Lie}_{X_{(c_1, \dots, c_n)}} \omega_1 + d_{\omega_2} d_{\omega_1} \tilde{H} \right) + \sum_{k=2}^{\infty} \epsilon^{2k} P_2^{(2k)}$$

with $\text{Lie}_e \Pi_\lambda = \omega_1$

Step 2: the last condition implies

$$\text{Lie}_e \left(\text{Lie}_{X_{(c_1, \dots, c_n)}} \omega_1 + d_{\omega_2} d_{\omega_1} \tilde{H} \right) = d_{\omega_1} \left(X_{\left(\frac{\partial c_1}{\partial u^1}, \dots, \frac{\partial c_n}{\partial u^n} \right)} - d_{\omega_2} (\text{Lie}_e \tilde{H}) \right) = 0.$$

Then there exists \tilde{K} s.t.

$$X_{\left(\frac{\partial c_1}{\partial u^1}, \dots, \frac{\partial c_n}{\partial u^n} \right)} = d_{\omega_2} (\text{Lie}_e \tilde{H}) + d_{\omega_1} \tilde{K}.$$

The above identity makes sense only if $c^i = \text{constant}$.

Non constant central invariants

Theorem

Let Π_λ a Poisson pencil with polynomial central invariants of maximal degree $n - 1$ and suppose that its dispersionless limit ω_λ is exact. Then there exists a Miura transformation reducing the pencil to the form

$$\tilde{\Pi}_\lambda = \omega_2 + \sum_{k=1}^{\infty} \epsilon^{2k} \tilde{P}_2^{(2k)} - \lambda \omega_1$$

with

$$\text{Lie}_e^{nk-k+1} \tilde{P}_2^{(2k)} = 0, \quad k = 1, 2, \dots$$

Homogeneous Poisson pencils I

Euler vector field $E = \sum_{i=1}^n r^i \frac{\partial}{\partial r^i}$

$$\mathrm{Lie}_E \omega_1 = (d-2)\omega_1$$

$$\mathrm{Lie}_E \omega_2 = (d-1)\omega_2.$$

Consequences

- $\mathrm{Lie}_E d_{\omega_1} - d_{\omega_1} \mathrm{Lie}_E = (d-2)d_{\omega_1}$
- $\mathrm{Lie}_E d_{\omega_2} - d_{\omega_2} \mathrm{Lie}_E = (d-1)d_{\omega_2}$
- $\mathrm{Lie}_E d_{\omega_1} d_{\omega_2} - d_{\omega_1} d_{\omega_2} \mathrm{Lie}_E = (2d-3)d_{\omega_1} d_{\omega_2}$

Homogeneous Poisson pencils II

Theorem

Let Π_λ be a homogeneous Poisson pencil. Suppose that the central invariants are homogeneous functions of degree D . Then there exists a Miura transformation reducing Π_λ to the form

$$\tilde{\Pi}_\lambda = \omega_2 + \sum_{k=1}^{\infty} \epsilon^{2k} \tilde{P}_2^{(2k)} - \lambda \omega_1$$

with

$$\text{Lie}_E \tilde{P}_2^{(2k)} = [(k+1)(d-1) + kD] \tilde{P}_2^{(2k)}, \quad k = 1, 2, \dots$$